WHAT IS CLAIMED IS:

1. A medical device comprising:

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a flexible shaft comprising a pulling member movable therein;

an actuating mechanism operatively associated with a proximal end of the flexible shaft;

an end effector associated with the distal end of the flexible shaft, wherein the end effector is operatively associated with a distal end of the pulling member; and

wherein the actuator mechanism has a first configuration in which the actuator mechanism is decoupled from the pulling member, and a second configuration wherein the actuator mechanism becomes operatively coupled to the pulling member to operate the end effector.

- 2. The device of Claim 1 wherein the actuator mechanism comprises an actuator movable from a first position wherein the actuator mechanism is decoupled from the pulling member to a second member wherein the actuator mechanism becomes operatively coupled to the pulling member.
- 3. The device of Claim 2 wherein the actuator is movable from the second position to a third position wherein the end effector is operated.
- 4. The device of Claim 1 wherein the actuating mechanism comprises a resilient member for operatively coupling the actuation member to the pulling member.
 - 5. The device of Claim 4 wherein the resilient member comprises a spring.
- 30 6. The device of Claim 5 wherein the resilient member comprises a torsion spring.

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- 7. The device of Claim 3 wherein the actuator is movable from the first position to the second position by squeezing with a single hand.
- 8. The device of Claim 1 wherein a proximal end of the pulling member is joined to a relatively larger diameter member, and wherein the actuator mechanism engages the relatively larger diameter member to provide coupling of the actuator mechanism to the pulling member.
- 9. The device of Claim 8 wherein the actuator mechanism engages the relatively
 10 larger diameter member by gripping engagement.
 - 10. The device of Claim 8 wherein the gripping engagement is provided by a resilient member.
- 15 11. The device of Claim 10 wherein the resilient member comprises a torsion spring.
 - 12. The device of Claim 1 wherein the end effector is selected from the group consisting of a biopsy forceps, grasping forceps, surgical scissors, extractors, and snares.

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